



# MULTITURN ABSOLUTE ENCODER EAM PROFIBUS



## Presentation

The Eltra multi-rotation Profibus encoder (Identification Number 0x0599) conforms to the standard Profibus DP described in the European Standard EN 50170 Volume 2 and in particular to the profile established for encoders "PROFIBUS Profile for Encoders, Order No. 3.062". The version with the Profibus DP interface keeps the same maximum resolution characteristics (8092 Pos/turn and 4096 revolutions) and efficiency characteristics of the stand-alone version, but adds the potential and flexibility typical of the Profibus DP network.

Via the Profibus DP network it is therefore possible to:

- Obtain the indication of the angular position from the encoder, during the *cyclical data exchange*
- Set the resolution on the turn and on the revolutions (during parameterizing)
- Change the predefined count increase direction (again during parameterizing)
- Perform the PRESET operation; in other words to set the encoder indication to a certain quota
- Read the operating diagnostic
- Have indications about the code supplied by the device.

On the device at a local it is also possible to:

- Display the ON/OFF status
- Display the device activity on the bus
- Give a RESET, in other words to set the current encoder code to 0
- Set the device address
- Insert the termination resistances on the bus, if needed
- Invert the count direction

## Device hardware installation

Installing the Eltra profibus encoder in a network requires the execution of the typical operations necessary for setting up any Profibus DP slave; the sequence of the steps can be summarised thus:

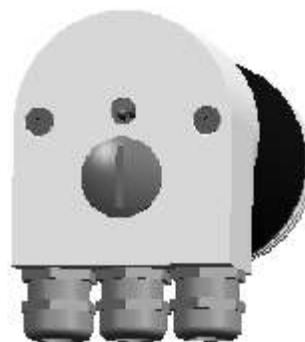
- 1 - *Commissioning* the slave on the master (see corresponding paragraph).
- 2 - Wiring the encoder into the Profibus network, with the insertion or not of terminations depending on the physical position the device occupies on the bus.
- 3 - Locally setting the address (which must be unique in the network and the same as the one chosen in point 1) for the slave.
- 4 - Preparing the master side application/s and setting up the Profibus network.

As we can see from the rear view of the encoder (see figure to the side) there is a led inspection window on the cover and a plug allowing access to the device local settings. The device operating status can be seen through the window by the two leds present. In particular, the green led signals power supply presence and must be permanently on, whilst the red led only goes out during the cyclical data exchange between the Profibus master that parameterized the encoder and the encoder itself.

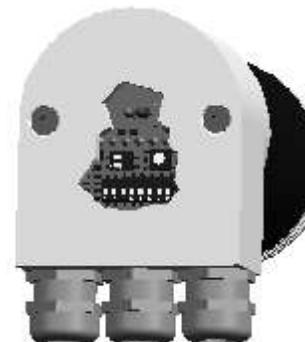
In the cut-away alongside, we can see the RESET button, or better the button for zeroing the code of the two dip-switches for line termination and the eight dip-switches for choosing the device address only to be used with the encoder at a standstill.

In the particular configuration shown in the cited figure, the two line termination contacts are in the OFF status and do not therefore foresee bus termination on the encoder.

Of the eight dip-switches available only the first seven are used for the slave address, given that the maximum number of devices that can be inserted in a Profibus network is 126 elements. Also, we must consider that contact 1 is the LSB of the address code, whilst contact 7 is the MSB. The eighth switch on the other hand is used for code inversion.



REAR COVER VIEW



CUT-AWAY DRAWING

**CONNECTION TO THE NETWORK.**

Concerning encoder connection to the Profibus DP network, cable access inside the device is through three skintops (only two can be used if preferred).

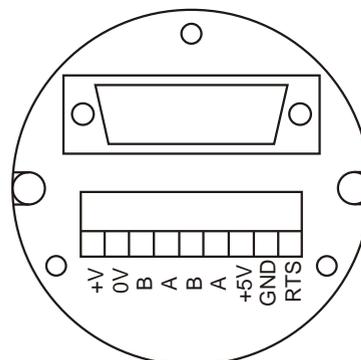
Usually, one is used for connection to the bus, one for network continuity connection and the last, optional, for local encoder power supply (if this is not distributed via the network and the RS-485 twin wire connection).



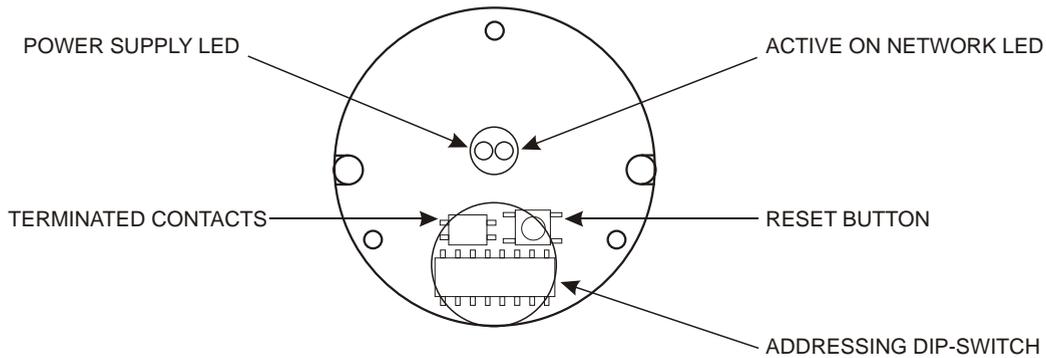
**ACCESS TO THE TERMINAL BLOCK**

To access the terminal block, unscrew the two screws on the rear plug and release the rear case from the main one by sliding it out from the sunken connector. Now connect the cables following the serigraphy on the connector, summarised in the following table:

<b>+V</b>	SUPPLY VOLTAGE
<b>0V</b>	GROUND
<b>B</b>	PROFIBUS DP LINE OUT (RED)
<b>A</b>	PROFIBUS DP LINE OUT (GREEN)
<b>B</b>	PROFIBUS DP LINE IN (RED)
<b>A</b>	PROFIBUS DP LINE IN (GREEN)
<b>+5V</b>	DC ISOLATED
<b>GND</b>	DC ISOLATED
<b>RTS</b>	REQUEST TO SEND

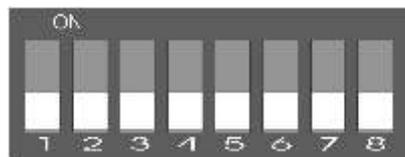


**N.B.:** To parameterize and configure the slave onto the Profibus DP master (*Commissioning* operation) it is necessary to use the "Exx\_0599.gsd" file supplied with the encoder and in any case available at the following site: [www.eltra.it](http://www.eltra.it).

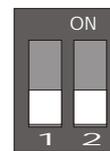


**SETTING THE DIP-SWITCHES**

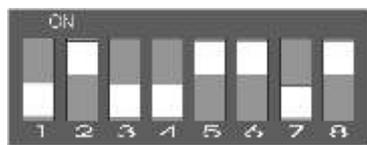
Below, we give examples of profibus line closing and device setting, plus the standard position of the address dip-switches.



STANDARD SETTING



STANDARD SETTING



LINE CLOSING

In this example a device LINE CLOSING address has been set equal to 1001101 from bit 2 to bit 8, corresponding to hexadecimal 77, whilst the first (1) bit corresponds to code inversion, which in this case is active.

**NETWORK CHARACTERISTICS:**

The physical means usually adopted when constructing a DP/FMS network is cable type A, which must have the following characteristics:

Parameter	Cable type A
Characteristic impedance in	135 ... 165 at a frequency of (3...20 Mhz)
Operating capacity (pF/m)	< 30
Loop resistance ( /km)	<=110
Core diameter (mm)	>0.64 *)
Core cross-section (mm <sup>2</sup> )	>0.34 *)

This cable permits optimum network utilisation. In other words, it is possible to reach the maximum permitted communication speed of 12 Mbaud. There are however the following limitations to the maximum physical dimensions of a bus segment:

Baud rate (kbit/s)	9.6	19.2	93.75	187.5	500	1500	12000
Range/Segment	1200 m	1200 m	1200 m	1000 m	400 m	200 m	100 m

Finally, we recall the physical and topographical characteristics of a profibus network:

Maximum number of stations participating in the exchange of user data	DP: 126 (address from 0..125) FMS: 127 (address from 0..126)
Maximum number of stations per segment including repeaters	32
Available data transfer rates in kbit/s	9.6, 19.2, 45.45, 93.75, 187.5, 500, 1500, 3000, 6000, 12000
Max. number of segments in series	According to EN 50170, a maximum of 4 repeaters are allowed between any two stations. Dependent on the repeater type and manufacturer, more than 4 repeaters are allowed in some cases. Refer to the manufacturer's technical specification for details.

## Ordering codes for multiturn absolute encoder

### PROFIBUS

In case of a particular Customer variant separate by a full stop

**EAM 63 A 4096 / 4096 B12/28 F X X 10 X 3 P3 R . XXX**

**EAM** = multiturn absolute encoder

**58** = body dimension  
**63** = body dimension  
**90** = body dimension  
**115** = body dimension

**A** = mod.EAM63 / 90 / 115  
**B** = mod.EAM58  
**C** = mod.EAM58  
**D** = mod.EAM63      Type of flanges  
**E** = mod.EAM63  
**F** = mod.EAM63  
**G** = mod.EAM63

**2 / 4 / 8 / 16 / 32 / 64 / 128 / 256 / 512 / 1024 / 2048 / 4096**      Turns

**2 / 4 / 8 / 16 / 32 / 64 / 128 / 256 / 512 / 1024 / 2048 / 4096 / 8192**      Resolutions  
 N.B.: For impulse availability contact our offices

**B** = Binary      Code

**12 ÷ 28**      Encoder power supply (Vdc)

**F** = PROFIBUS      Electronics output configuration  
 N.B.: For the optionals on the output configurations contact our offices

**XXX** = Special Customer variants indicated by a progressive number from 001 to 999

**R** = radial

**P2** = two skintop  
**P3** = three skintop

**3** = 3000 with IP66      R.P.M.  
**6** = 6000

**X** = IP54      Protection  
**S** = optional IP66 excluding EA63F/G --EAM115

**6** = ∅ 6g6 mm -- 58B  
**8** = ∅ 8g6 mm -- 58B -- 63A / D / E -- 90A  
**9** = ∅ 9.52g6 mm -- 63A / D / E -- 90A      Shaft diameter  
**10** = ∅ 10g6 mm -- 58B / C -- 63A / D / E -- 90A -- 115A  
**11** = ∅ 11g6 mm -- 115A

**8** = ∅ 8H7 mm  
**9** = ∅ 9H7 mm  
**10** = ∅ 10H7 mm      Hole diameter only for mod.63F / G  
**12** = ∅ 12H7 mm  
**14** = ∅ 14H7 mm  
**15** = ∅ 15H7 mm

**X** = not to utilize      Options

**X** = not to utilize      Logics

### Enviromental Characteristics

<b>Protection</b>	IP54 IP66 optional --58B/C --63A/D/E --90A
<b>Operating Temperature</b>	0° ÷ +60°C
<b>Storage Temperature</b>	-15° ÷ +70°C

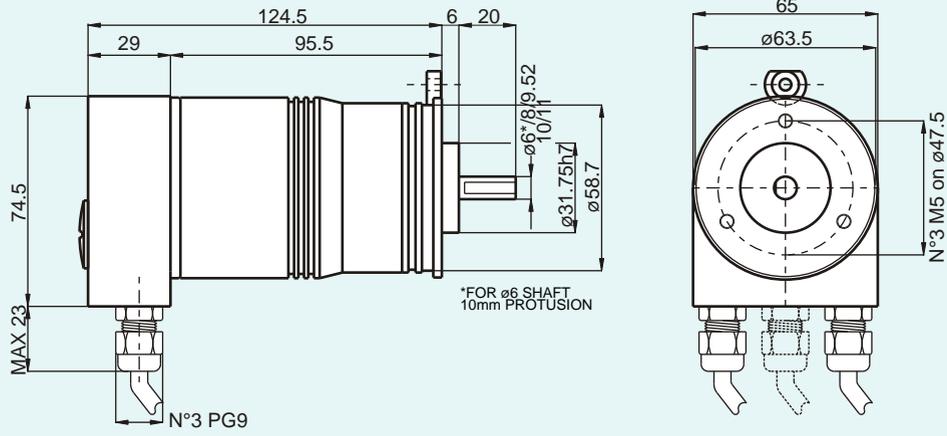
### Electronic Characteristics

<b>Turns</b>	2 / 4 / 8 / 16 / 32 / 64 / 128 / 256 / 512 / 1024 / 2048 / 4096
<b>Resolutions</b>	2 / 4 / 8 / 16 / 32 / 64 / 128 / 256 / 512 / 1024 / 2048 / 4096 / 8192
<b>Power supply</b>	12 ÷ 28 Vdc
<b>Current consumption without load</b>	300 mA
<b>Electronic of Bus</b>	LINE DRIVER (RS485)
<b>Max output frequency</b>	100 KHz output code $F = \frac{RPM \times Resolution}{60}$
<b>Accuracy</b>	+/- 1/2 LSB
<b>Bus Max Frequency</b>	12 Mbaud

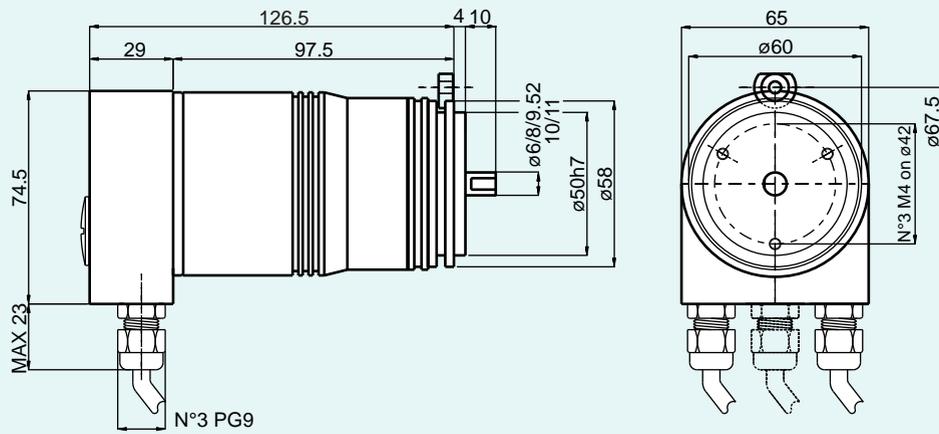
### Mechanical Characteristics

<b>Shaft diameters (mm)</b>	∅6 g6 -- 58B ∅8 g6 -- 58B -- 63A/D/E -- 90A ∅9.52(3/8") g6 -- 63A/D/E -- 90A ∅10 g6 -- 58B/C -- 63A/D/E -- 90A -- 115A ∅11 g6 -- 115A
<b>Hole diameters (mm)</b>	∅8 H7 --63F/G ∅9 H7 --63F/G ∅10 H7 --63F/G ∅12 H7 --63F/G ∅14 H7 --63F/G ∅15 H7 --63F/G
<b>R.P.M. Max</b>	6000 continuos 3000 continuos for --63G/F 3000 with Ip66
<b>Shock</b>	50 G per 11 msec
<b>Vibrations</b>	10G 10 ÷ 2000 Hz
<b>Bearings life</b>	10 <sup>9</sup> revolutions
<b>Bearings</b>	n°2 ball bearings
<b>Shaft material</b>	Stainless steel AISI303
<b>Body material</b>	Aluminium -UNI 9002/5- (D11S)
<b>Cover material</b>	Aluminium alloy 6060
<b>Flange material</b>	Aluminium -UNI 9002/5- (D11S)
<b>Weight</b>	~ 800 g --58B/C--63A/D/E/F/G ~ 1000 g --90A--115A

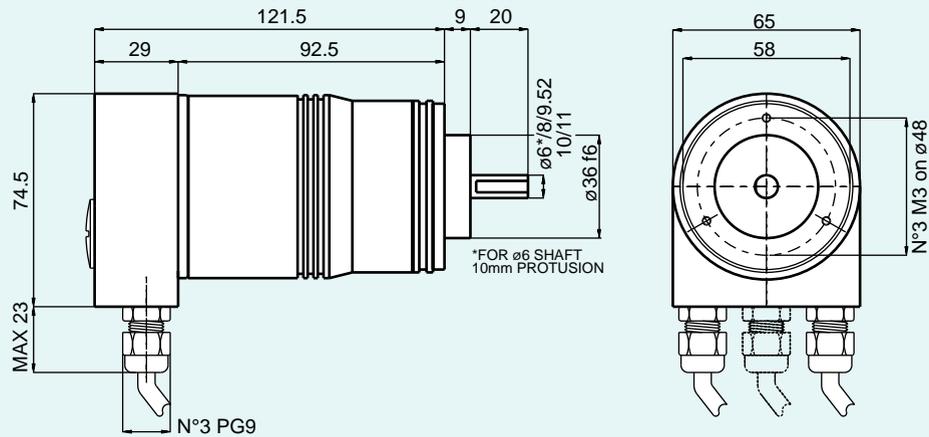
### EAM63A



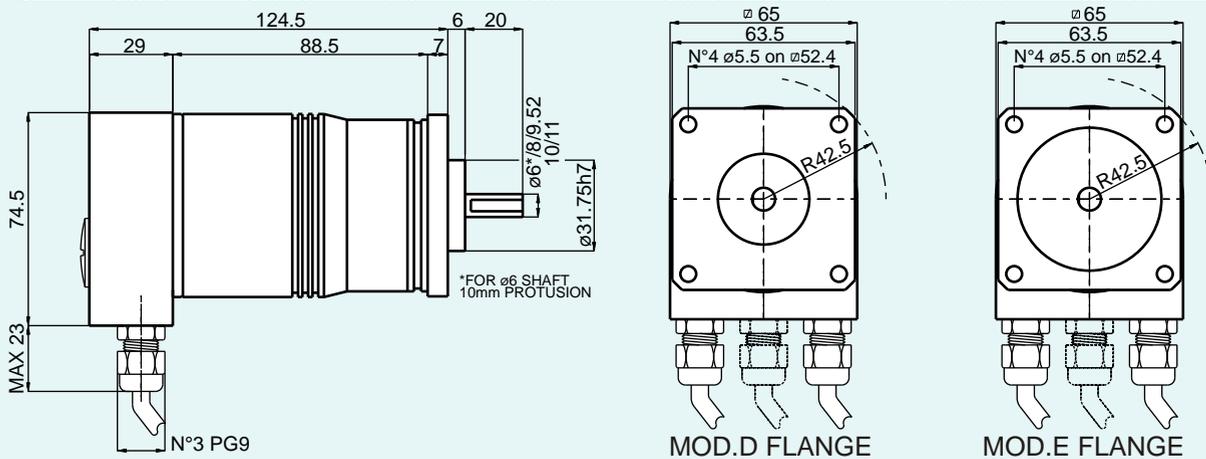
### EAM58B



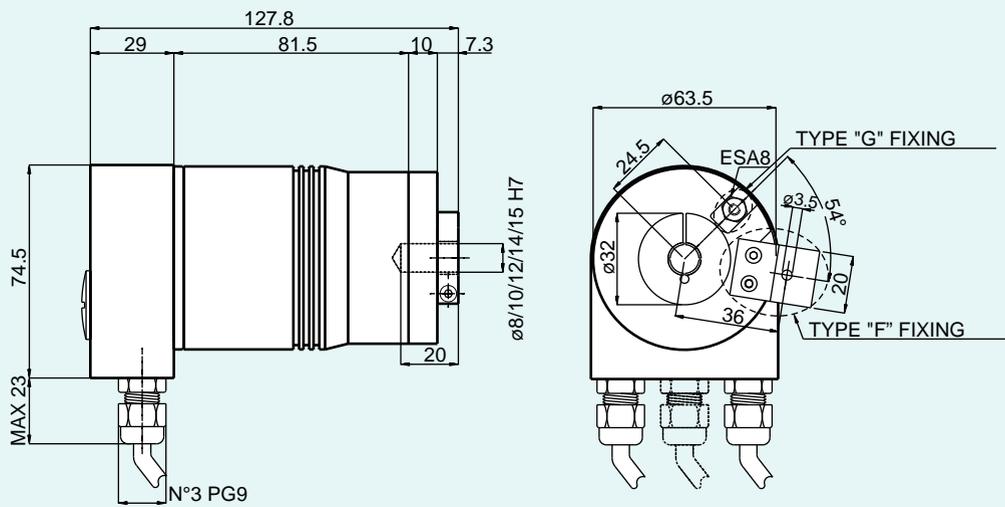
### EAM58C



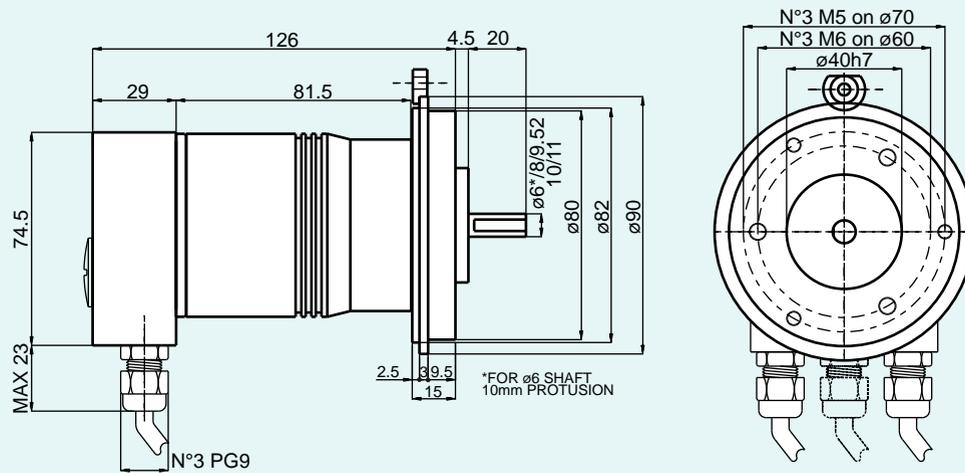
### EAM63D - EAM63E



## EAM63F - EAM63G



## EAM90A



## EAM115A

